

Syllabus and suggested problems for the Mid term. are included here.

Please go through

- suggested problems.
- H.W. 1
- H.W 2 (problem 2).

while preparing for the midterm.

Material to revise for the test:

- Vector space, basis, linear independence of vectors.
- Linear Transformation, Range, Null space.
- Inner product of vector.
- Adjoint of a linear transformation.
- Trace and determinant of a square matrix.
- Eigenvalues, Eigenvectors, gen. eigenvectors, similarity trans. Jordan canonical forms.

- Solⁿ to homogeneous eqn.

$$\dot{x} = A(t)x(t).$$

Peano Baker series.

Fundamental matrix. $\phi(t, t_0)$.

- Calculating exponential of matrices.

- Controllability / controllability

Gramian.

- Rank test for controllability of Time Invariant systems.

$$\dot{x} = Ax + bu.$$

Note: Floquet Theory will be excluded from the test.

① Let V be a set of matrices defined as follows:

①

(a) $V_1 \triangleq \{ A \in \mathbb{R}^{2 \times 2} : \text{trace } A = 0 \}$.

Is V a vector space under usual matrix addition and scalar multiplication?

(b) $V_2 \triangleq \{ A \in \mathbb{R}^{2 \times 2} : \det A = 0 \}$.

Is V a vector space under usual matrix addition and scalar multiplication?

Find a basis for those V that are vector spaces?

② Is it true that

$$e^{(A+A^{-1})t} = e^{At} e^{A^{-1}t}$$

$$e^{(A+A^3)t} = e^{At} e^{A^3t}$$

Why or why not?

(3) Consider a mapping L from $\mathbb{R}^{2 \times 2}$ to $\mathbb{R}^{2 \times 2}$ (2)

as follows:

$$L: \mathbb{R}^{2 \times 2} \rightarrow \mathbb{R}^{2 \times 2}$$

$$A \mapsto \frac{1}{2}[A - A^T]$$

- Is L a linear transformation? Argue why or why not.
- Describe the range and nullspace of L .
- Calculate rank and nullity of L .
- Can you describe L using any matrix.
 - you need to choose a basis of $\mathbb{R}^{2 \times 2}$
 - you need to decide an order of the matrix
 - Find it.
- Define inner product in $\mathbb{R}^{2 \times 2}$ as follows:
 $\langle A, B \rangle = \text{trace}(AB^T)$.
What would be the adjoint of L ??

③ Describe the null space of $\text{adj} L$ and show that this space is perpendicular to every vector in the range space of L .

④
$$\begin{pmatrix} \dot{z}_1 \\ \dot{z}_2 \\ \dot{z}_3 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ t & 1 \\ 0 & t \end{pmatrix} \begin{pmatrix} u_1(t) \\ u_2(t) \end{pmatrix}$$

Assume $z_1(0) = z_2(0) = z_3(0) = 0$. Describe the set of all pts in \mathbb{R}^3 that you can reach by a suitable choice of $u_1(t), u_2(t), 0 \leq t \leq 1$

- Take $t_0 = 0, t_1 = 1$
- Find range of $W(0, 1)$.

⑤ Is the state equation on Lec 3, page 29, controllable??

- calculate $\text{rank} [B, AB, A^2B]$.

⑥ Let

$$A = \begin{pmatrix} 1 & 2 \\ 0 & 1 \end{pmatrix}$$

(i) Calculate A^{99} .

(ii) Calculate e^{At} .

⑦ Let

$$A = \begin{pmatrix} 1 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 1 \end{pmatrix}$$

(i) Calculate A^{103} .

(ii) Calculate e^{At} .

⑧ Consider the state space eqn.

$$\dot{\underline{x}} = A\underline{x} + bu$$

where A is given by problem ⑦

$$b = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}, \underline{x}(0) = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}$$

$$u(\sigma) = 1 \quad \sigma \geq 0$$

(i) Calculate $\underline{x}(t)$.

(ii) Write down the controllability gramian matrix $\bar{W}(0,1)$ from page 12, Lec 4.

⑨ Let $A(t)$ be a square matrix:

⑤

$$A(t) \int_{t_0}^t A(\sigma) d\sigma =$$

$$\left[\int_{t_0}^t A(\sigma) d\sigma \right] A(t) \quad \forall t.$$

then.

$$\Phi(t, t_0) = \exp \left[\int_{t_0}^t A(\sigma) d\sigma \right]$$

(show the above fact).

$$\text{If } A(t) = \begin{pmatrix} t & t^2 \\ t^2 & t \end{pmatrix}$$

(i) Calculate the 1st 3 terms of the $\Phi(t, t_0)$.

(ii) Calculate $\det[\Phi(t, t_0)]$ using Lec 5 page 28.

(10) Cayley Hamilton Th^m says that

if A is a $n \times n$ matrix, A^n can be written as a linear combination of lower powers

of A . i.e.

$$A^n = \alpha_0 I + \alpha_1 A + \dots + \alpha_{n-1} A^{n-1}.$$

It would follow that

$$e^A = \beta_0 I + \beta_1 A + \dots + \beta_{n-1} A^{n-1}.$$

if A is $n \times n$.

Using the above recipe, calculate

$$\Phi(t, 0)$$

in problem (9).