

H. W. 6 (answers)

①

① Ans:

$$b = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} ; Ab = \begin{pmatrix} 0 \\ 1 \\ -3 \end{pmatrix} ; A^2 b = \begin{pmatrix} 1 \\ -3 \\ 7 \end{pmatrix}$$

Define

$$P = \begin{pmatrix} 1 & 0 & 0 \\ -3 & 1 & 0 \\ 7 & -3 & 1 \end{pmatrix} ; P^{-1} = \begin{pmatrix} 1 & 0 & 0 \\ 3 & 1 & 0 \\ +2 & 3 & 1 \end{pmatrix}$$

$P^{-1} A P =$

$$\begin{pmatrix} 1 & 0 & 0 \\ 3 & 1 & 0 \\ 2 & 3 & 1 \end{pmatrix} \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -1 & -2 & -3 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ -3 & 1 & 0 \\ 7 & -3 & 1 \end{pmatrix} \\ = \begin{pmatrix} 1 & 0 & 0 \\ 3 & 1 & 0 \\ 2 & 3 & 1 \end{pmatrix} \begin{pmatrix} -3 & 1 & 0 \\ 7 & -3 & 1 \\ -16 & 7 & -3 \end{pmatrix} = \begin{pmatrix} -3 & 1 & 0 \\ -2 & 0 & 1 \\ -1 & 0 & 0 \end{pmatrix}$$

$$P^{-1}b = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$$

Thus

$$P = \begin{pmatrix} 1 & 0 & 0 \\ -3 & 1 & 0 \\ 7 & -3 & 1 \end{pmatrix}$$

$$F = \begin{pmatrix} -3 & 1 & 0 \\ -2 & 0 & 1 \\ -1 & 0 & 0 \end{pmatrix} \quad g = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$$

This is the controllable canonical form.

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~~② $A = \begin{pmatrix} -5 & 1 & 0 \\ 4 & 0 & 1 \\ 39 & 0 & 1 \end{pmatrix}, b = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$~~

~~$Ab = \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix}, A^2b = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$~~

~~Define~~

~~$P = \begin{pmatrix} 0 & 0 & 1 \\ 0 & 1 & 1 \\ 1 & 1 & 1 \end{pmatrix}$~~

② Ans.

③

(i) Characteristic polynomial of A is given by

$$\det(\lambda I - A) =$$

$$\lambda^3 + 4\lambda^2 - 9\lambda + 43.$$

Thus the controllable canonical form is

$$A_c = \begin{pmatrix} -4 & 1 & 0 \\ 9 & 0 & 1 \\ -43 & 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} = b$$

Moreover the feedback canonical form is

$$A_f = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -43 & 9 & -4 \end{pmatrix}, \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} = b.$$

(ii) The matrix P_1 that will transform

$$(A, b) \xrightarrow{P_1} (A_c, b)$$

$$\text{ie } P_1^{-1} A P_1 = A_c, P_1^{-1} b = b$$

$$\text{is given by } P_1 = (A^2 b, A b, b)$$

(4)

P_1 is computed as

$$P_1 = \begin{pmatrix} 1 & 0 & 0 \\ 1 & 1 & 0 \\ 1 & 1 & 1 \end{pmatrix}$$

\uparrow \uparrow \uparrow
 A^2b Ab b

(iii) The matrix Q_2 that will transform

$$(A_f, b) \xrightarrow{Q_2} (A_c, b) \quad \left[\text{as was done in problem 1} \right]$$

$$\text{RE } Q_2^{-1} A_f Q_2 = A_c, \quad Q_2^{-1} b = b$$

is given by

$$Q_2 = (A_f^2 b, A_f b, b)$$

$$Q_2 = \begin{pmatrix} 1 & 0 & 0 \\ -4 & 1 & 0 \\ 25 & -4 & 1 \end{pmatrix}$$

(iv) Define $P_2 = Q_2^{-1}$, we conclude that the matrix P_2 will transform

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$$(A_c, b) \xrightarrow{P_2} (A_f, b)$$

ie $P_2^{-1} A_c P_2 = A_f, P_2^{-1} b = b$

(v) Define $P = P_1 P_2$. It follows that

$$P^{-1} A P = A_f, P^{-1} b = b.$$

ie the matrix P will transform

$$(A, b) \xrightarrow{P} (A_f, b)$$

(Note that this is a new and perhaps easier method to calculate P not discussed in my notes)

----- x -----

(vi) calculate P_2

$$Q_2^{-1} = \begin{pmatrix} 1 & 0 & 0 \\ 4 & 1 & 0 \\ -9 & 4 & 1 \end{pmatrix} = P_2$$

(vi)

$$P = \begin{pmatrix} 1 & 0 & 0 \\ 1 & 1 & 0 \\ 1 & 1 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 4 & 1 & 0 \\ -9 & 4 & 1 \end{pmatrix}$$

$$= \begin{pmatrix} 1 & 0 & 0 \\ 5 & 1 & 0 \\ -4 & 5 & 1 \end{pmatrix}$$

(vi) Starting with

$$\dot{x} = Ax + bu$$

if we define

$$x = Pz$$

we obtain

$$\dot{z} = A_f z + b u$$

Define F_1 such that $u = F_1 z$ would place

the characteristic polynomial of

$$A_f + b F_1$$

$$\text{at } (\lambda + 1)^3 = \lambda^3 + 3\lambda^2 + 3\lambda + 1$$

We would have

$$A_f + b F_1 = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -1 & -3 & -3 \end{pmatrix}$$

If $F_1 = (f_1 \ f_2 \ f_3)$ it follows that

$$f_1 - 43 = -1 \qquad f_1 = 42$$

$$f_2 + 9 = -3 \qquad f_2 = -12$$

$$f_3 - 4 = -3 \qquad f_3 = 1$$

$\therefore F_1 = (42 \ -12 \ 1)$ will do the job.

(vi) Writing

$$u = F_1 Z = F_1 P^{-1} X$$

we would have

$$F = F_1 P^{-1} = (42 \ -12 \ 1) \begin{pmatrix} 1 & 0 & 0 \\ -5 & 1 & 0 \\ 29 & -5 & 1 \end{pmatrix}$$

$$= (131 \ -17 \ 1)$$

$F = (131 \ -17 \ 1)$
 wow, I finally have
 the answer.

③ Ans

$$(i) \quad B = \begin{pmatrix} 0 & 0 \\ 1 & 0 \\ 0 & 1 \\ 0 & 0 \end{pmatrix}$$

$$\text{rank}[B, AB] = 4$$

$$AB = \begin{pmatrix} 1 & 3 \\ 0 & 4 \\ 0 & -1 \\ 0 & -7 \end{pmatrix}$$

Hence the system is controllable

(ii)

b_1	b_2
Ab_1	Ab_2

← they are all independent

$2 \quad 2$

$(2, 2)$ are the Kronecker indices.

(iii) The Kronecker controllable canonical form (9) (8)
 is given by

$$A_c = \begin{pmatrix} \times & 1 & \times & 0 \\ \times & 0 & \times & 0 \\ \times & 0 & \times & 1 \\ \times & 0 & \times & 0 \end{pmatrix} \quad B_c = \begin{pmatrix} 0 & 0 \\ 1 & \times \\ 0 & 0 \\ 0 & 1 \end{pmatrix}$$

(iv) Define

$$P = (Ab_1, b_1, Ah_2, h_2)$$

$$= \begin{pmatrix} 1 & 0 & 3 & 0 \\ 0 & 1 & 4 & 0 \\ 0 & 0 & -1 & 1 \\ 0 & 0 & -7 & 0 \end{pmatrix}$$

$$(v) A^2 b_1 = \begin{pmatrix} 2 \\ 3 \\ 5 \\ 9 \end{pmatrix} = \frac{41}{7} Ab_1 + \overset{57/7}{\downarrow} b_1 - \frac{9}{7} Ah_2 + \frac{26}{7} h_2$$

First column of A_c is

$$\begin{pmatrix} 41/7 \\ 57/7 \\ -9/7 \\ 26/7 \end{pmatrix}$$

(vi) $A^2 b_2 =$

$$\begin{pmatrix} 2 & 1 & 3 & 0 \\ 3 & 0 & 4 & 0 \\ 5 & 0 & -1 & 1 \\ 9 & 0 & -7 & 0 \end{pmatrix} \begin{pmatrix} 3 \\ 4 \\ -1 \\ -7 \end{pmatrix} = \begin{pmatrix} 7 \\ 5 \\ 9 \\ 34 \end{pmatrix}$$

$$= \frac{151}{7} A b_1 + \frac{171}{7} b_1 - \frac{34}{7} A b_2 + \frac{29}{7} b_2$$

3rd column of A_c is $\begin{pmatrix} 151/7 \\ 171/7 \\ -34/7 \\ 29/7 \end{pmatrix}$

(vii)

$$A_c = \begin{pmatrix} 41/7 & 1 & 151/7 & 0 \\ 57/7 & 0 & 171/7 & 0 \\ -9/7 & 0 & -34/7 & 1 \\ 26/7 & 0 & 29/7 & 0 \end{pmatrix}, B_c = \begin{pmatrix} 0 & 0 \\ 1 & 0 \\ 0 & 0 \\ 0 & 1 \end{pmatrix}$$

Kronecker controllable canonical form.

(viii)

(11)

We want

$$A_f = \begin{pmatrix} 0 & 1 & 0 & 0 \\ x & x & x & x \\ 0 & 0 & 0 & 1 \\ x & x & x & x \end{pmatrix}, B_f = \begin{pmatrix} 0 & 0 \\ 1 & 0 \\ 0 & 0 \\ 0 & 1 \end{pmatrix}$$

Q: Here is a problem for you.

Find P_1 :

$$P_1^{-1} A_c P_1 = A_f, P_1^{-1} B_c = B_f$$

Note that

$$A_f = \begin{pmatrix} 0 & 1 & 0 & 0 \\ 57/7 & 41/7 & 171/7 & 151/7 \\ 0 & 0 & 0 & 1 \\ 26/7 & -9/7 & 29/7 & -34/7 \end{pmatrix}, B_f = \begin{pmatrix} 0 & 0 \\ 1 & 0 \\ 0 & 0 \\ 0 & 1 \end{pmatrix}$$

Look at pages 33 & 44 of
Lec10

(ix) (a) Let F_1 be described as

$$F_1 = \begin{pmatrix} f_1 & f_2 & f_3 & f_4 \\ f_5 & f_6 & f_7 & f_8 \end{pmatrix}$$

Choose $f_1 = -57/7, f_2 = -41/7, f_3 = -\frac{171}{7} + 1$

$f_4 = -\frac{151}{7}, f_5 = -\frac{26}{7} - 44$

$f_6 = 9/7 + 15, f_7 = -29/7 - 29, f_8 = \frac{34}{7} - 19$

We calculate

$$A_f + B_f F_1 =$$

$$\begin{pmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ -44 & 15 & -29 & -19 \end{pmatrix}$$

which has char. polynomial at .

$$\lambda^4 + 19\lambda^3 + 29\lambda^2 - 15\lambda + 44$$

X

$$(A, B) \xrightarrow{P} (A_c, B) \xrightarrow{P_1} (A_f, B)$$

$$(A, B) \xrightarrow{PP_1} (A_f, B)$$

Require

$$F = F_1 (PP_1)^{-1}$$

I have P.
You calculate P₁
and finish the job.

4) Ans:

I) yes because e has rank 6.

II)

b_1	b_2	b_3
Ab_1	Ab_2	
A^2b_1		
3	2	1

Kronecker indices are (3, 2, 1).

III) Kronecker controllable canonical form

$$A_c = \begin{pmatrix} \times & 1 & 0 & \times & 0 & \times \\ \times & 0 & 1 & \times & 0 & \times \\ \times & 0 & 0 & \times & 0 & \times \\ \times & 0 & 0 & \times & 1 & \times \\ \times & 0 & 0 & \times & 0 & \times \\ \times & 0 & 0 & \times & 0 & \times \end{pmatrix}, B_c = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 1 & \times & \times \\ 0 & 0 & 0 \\ 0 & 1 & \times \\ 0 & 0 & 1 \end{pmatrix}$$

(IV) De fine

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$$P = (A^2 b_1, Ab_1, b_1, Ah_2, h_2, b_3)$$

$$A^3 b_1 = 0 A^2 b_1 + 1 Ab_1 + 0 b_1 + 1 Ah_2 + 0 h_2 - 1 b_3$$

co-ordinates are (0 1 0 1 0 -1)

$$A^2 b_2 = -7 A^2 b_1 + 0 Ab_1 + 0 b_1 + 6 Ah_2 + 4 h_2 + 0 b_3$$

co-ordinates are (-7 0 0 6 4 0)

$$A b_3 = 0 A^2 b_1 + 0 Ab_1 + 3 b_1 - 5 Ah_2 + 2 h_2 + 0 b_3$$

co-ordinates are (0 0 3 -5 2 0).

$$\therefore A_c = \left(\begin{array}{ccc|cc} 0 & 1 & 0 & -7 & 0 \\ 1 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 3 \\ \hline 1 & 0 & 0 & 6 & -5 \\ 0 & 0 & 0 & 4 & 2 \\ \hline -1 & 0 & 0 & 0 & 0 \end{array} \right); B_c = \left(\begin{array}{ccc} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{array} \right)$$

Q: Can you transform

$$(A_c, B_c) \mapsto (A_f, B_f)$$

similar to what we did in
problem 3.

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